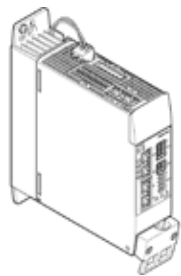


servo drive CMMT-AS-C4-3A-EC-S1

Part number: 5340820

☆ Core product range

FESTO



Data sheet

Feature	Value
Mounting type	Mounting plate, bolted
Assembly position	Free convection Vertical
Product weight	1,400 g
Display	LED green/yellow/red
Control elements	Optional: control unit CDSB
Conforms to standard	EN 61800-3 EN 61800-5-1 EN 61800-5-2 EN ISO 13849-1
Based on the standard	EN 50581 EN 60204-1 EN 61508-1 EN 61508-2 EN 61508-3 EN 61508-4 EN 61508-5 EN 61508-6 EN 61508-7 EN 61800-2 EN 62061
Authorisation	RCM Mark TÜV c UL us - Listed (OL)
KC mark	KC-EMV
CE mark (see declaration of conformity)	to EU directive for EMC to EU directive for machinery to EU directive low-voltage devices in accordance with EU RoHS directive
Certificate issuing department	TÜV Rheinland 01/205/5640.00/18 UL E331130
Storage temperature	-25 ... 55 °C
Ambient temperature	0 ... 50 °C
Note on ambient temperature	Power must be reduced by 3%/°C at ambient temperatures above 40°C.
UL ambient temperature	0 ... 40 °C
Relative air humidity	5 - 90 % non-condensing
Max. installation height	2,000 m
Note on max. installation height	From 1000 m, power reduction by 1% per 100 m
Protection class	IP20
Safety class	I
Overvoltage category	III
Degree of contamination	2
Surge strength	6 kV
Materials note	Contains PWIS substances Conforms to RoHS

Feature	Value
Nominal operating voltage, phases	Single-phase
Nominal operating voltage, AC	230 V
Permissible voltage fluctuation	-20 % / +15 %
Input voltage range AC	100 ... 230 V
Line frequency	48 ... 62 Hz
Nominal current, load supply	5.6 A
Peak current, load supply	16.8 A
Active PFC	No
Mains filter	Integrated
System voltage to EN 61800-5-1	300 V
Max. short circuit protection of the mains	100 kA
Mains types	TT TN IT
Nominal voltage, load supply DC	320 V
Permissible range, load supply	-20 %/+15 %
Max. intermediate circuit voltage, DC	395 V
Braking resistor, integrated	100 Ohm
Braking resistance pulse power	1.6 kW
Pulse energy for braking resistor	230 Ws
Nominal power braking resistor (IEC)	23 W
Braking resistor, external	67 ... 100 Ohm
Max. continuous output of the external braking resistor (IEC)	350 W
Nominal DC voltage, logic power supply	24 V
Permissible range, logic voltage	± 20 %
Current consumption, logic power supply without clamping brake	0.5 A
Current consumption for logic supply with locking brake	1.5 A
Max. current consumption for logic supply, holding brake and I/O	2.3 A
Output voltage range AC	3x (0 – Input) V
Effective nominal current per phase	4 A
Effective peak current per phase	12 A
Max. peak current duration	2 s
Nominal controller power	700 W
Peak power	2,000 W
Output frequency	0 ... 599 Hz
Max. length of motor cable without external mains filter	25 m
Max. output current of holding brake	1 A
Max. voltage drop from logic supply to brake output	0.8 V
Number of inputs for motor temperature sensor	1
Controller operating mode	Cascade controller P position controller PI speed controller PI current regulator for F or M Profile operation with record and direct mode Interpolated mode via fieldbus Synchronised operating modes Homing Setting-up Autotuning
Operating mode	Field-oriented closed-loop control Position resolution 24 bit/U Sampling rate 16 kHz PWM at 8 or 16 KHz Vector modulation with 3rd harmonic Real-time data acquisition 2x Input-Capture (x, v, F) 2x Output-Trigger (x, v, F) 2x position encoder input 1x SYNC interface for encoder emulation or encoder input
Ethernet interface, function	Parameterisation and commissioning
Ethernet interface, protocol	TCP/IP

Feature	Value
Fieldbus interface, protocol	EtherCAT
Fieldbus coupling	EtherCAT
Communications profile	CiA402 CoE (CANopen over EtherCAT) EoE (Ethernet over EtherCAT) FoE (File over EtherCAT)
Process interface	Interpolated Mode CSP Interpolated Mode CSV Interpolated Mode CST I/O mode for 256 position sets
Fieldbus interface, transmission rate	100 Mbit/s
Fieldbus interface, type of connection	2x socket
Fieldbus interface, connection technology	RJ45
Encoder interface, function	ENDAT 2.1 encoder ENDAT 2.2 encoder Hiperface encoder Incremental encoder Nikon SIN/COS encoder
Encoder interface 2, function	Incremental encoder SIN/COS encoder
Synchronisation interface, function	Encoder emulation A/B/Z Encoder input A/B/Z Pulse/direction signals CLK/DIR Counting signals CW/CCW
Encoder interface output, characteristics	1 MHz maximum output frequency max. 16384 ppr
Encoder interface input, characteristics	1 MHz maximum output frequency max. 16384 ppr
Number of digital logic inputs	12
Input circuit logic	PNP (positive-switching)
Logic input characteristics	Freely configurable to a given extent Safety inputs in some cases Not electrically isolated
Specification, logic input	Based on IEC 61131-2, type 3
Logic input working range	-3 ... 30 V
Number of high-speed logic inputs	2
Time resolution of high-speed logic inputs	1 µs
Number of 24 V DC digital logic outputs	6
Switching logic, outputs	PNP (positive-switching)
Digital logic output characteristics	Freely configurable to a given extent Not electrically isolated Diagnostics outputs in some cases
Max. current, digital logic outputs	20 mA
Number of high-speed switching outputs	2
Time resolution of high-speed switching outputs	1 µs
Number of floating switching outputs	1
Max. current of the floating switching outputs	50 mA
Number of analogue setpoint inputs	1
Setpoint input characteristics	Differential inputs Can be configured for speed in RPM Configurable for current/force
Setpoint input working range	± 10 V
Operating range Analogue inputs	± 10 V
Setpoint input impedance	70 kOhm
Safety function	Safe brake control (SBC) Safe torque off (STO) Safe stop 1 (SS1)
Safety Integrity Level (SIL)	Safe brake control (SBC) / SIL 3 / SILCL 3 Safe torque off (STO)/SIL 3/SILCL 3
Performance level (PL)	Safe brake control (SBC) / category 3, Performance Level e

Feature	Value
	Safe Torque off (STO)/Category 4, Performance Level e
Diagnostic coverage	97 %
SFF Safe Failure Fraction	99 %
Hardware fault tolerance	1
Number of safe 2-pin inputs	2
Number of diagnostic outputs	2